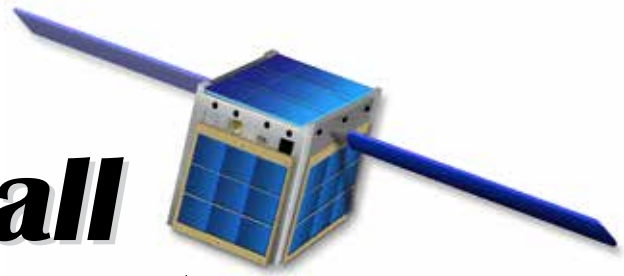


CubeSat and Small Satellite Components



CubeSat spacecraft are miniaturized satellites created for a variety of space applications and typically have the volume of a 10 centimeter cube and a mass of no more than 1.33 kilograms. Standard components are generally used in these systems although more advanced technologies may also be an option. Satellites that have an overall mass of under 500 kilograms are often referred to as small satellites.

Moog Components Group has components on countless space programs. Our 50 plus years of space heritage is being leveraged to provide small, efficient, best value products for the growing CubeSat and small satellite market.

Our components are designed to meet:

- Extreme temperature ranges
- Launch vibration and shock
- NASA material guidelines

All designs are tailored for maximum performance in the smallest volume possible. Size, weight and power are driving design criteria.

Slip Rings

Long-life fiber brush designs eliminate the need for lubricant on the contacting system. Small volume designs in drum or platter style configurations are available.

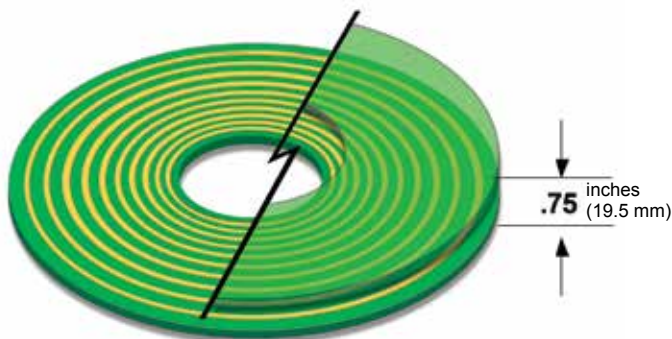
Drum: Model 3848

Diameter: 0.75 inches (19.05 mm)
 Length: 1 inch (25.4 mm)
 10 rings space rated for 0.5 A and 50 V each
 Housed with bearings

Platter Separates: Model 1021621

For space requirements, platter separates are an ideal solution. Units supplied generally consist of a slip ring based on a printed circuit board style and a matching brush block or board depending on the requirements.

Diameter: 2 inches (50.8 mm)
 Height: 0.75 inch as a set (19.05 mm)
 10 rings at 0.5 A, 50 V each



Motors

Frameless, brushless motors are designed for applications that require high torque density. The designs are optimized to minimize power for maximum efficiency and long life capability.

DB-1500-J-1ES Matrix™ Series Motor Specifications		
Size Constants	Units	Value
Peak Torque, T_P	oz-in (Nm)	21 (0.149)
Motor Constant, K_M	oz-in / \sqrt{W} (Nm / \sqrt{W})	2.76 (0.019)
Weight	oz (kg)	2.7 (0.076)
Motor Inertia, J_M	oz-in-s ² (kg m ²)	9.08E-05 (2.0E-09)
Friction Torque, T_F	oz-in (Nm)	0.4 (0.0028)
Electrical Time Constant, T_E	ms	0.28
Mechanical Time Constant, T_M	ms	1.68
Temperature Rise, TPR	°C / W	13.4
Number of Poles		8
Number of Phases		3 "Y"
Winding Constants	Units	Value
Torque Sensitivity, K_T	oz-in / amp \pm 10% (Nm / amp)	1.43
Back EMF, K_E	V per rad / s \pm 10%	0.010
Terminal Resistance, R_M	ohms \pm 10%	0.268
Terminal Inductance, L_M	mH \pm 30%	0.076
Voltage, Stalled at Peak Torque, V_P	Volts	4.0
Amps at Peak Torque, I_P	Amps	15

Performance is based on a DB-1500-J-1ES Matrix™ Series motor with the following dimensions:

Diameter: 1.5 inches (38 mm)
 Height: 0.9 inches (22.86 mm)

Resolvers

Rugged motion feedback sensors provide velocity and / or position feedback for electronic control, as well as DC motor commutation. There are no internal electronics or optics and resolvers are unaffected by electrical noise, heat, shock and vibration. No active or contacting parts for extended life.

Single-Speed - SSH-12-A-2

Outer Diameter: 1.19 inches (30.22 mm)
 Inner Diameter: 0.56 inches (14.22 mm)
 Height: 0.23 inches (5.84 mm)

Multi-Speed - SSJH-15-A-2

Outer Diameter: 1.5 inches (38.1 mm)
 Inner Diameter: 0.70 inches (17.78 mm)
 Height: 0.37 inches (9.40 mm)

Resolver Specifications										
Function	Primary Winding	Speed	Input (Voltage / Hz)	Max Error (Accuracy) (+/-)	Trans. Ratio	Phase Shift (DEG)	Max Null V (mV)	Pin (mW)	Impedances	
									Zpo	Zso
Single Speed - Part Number SSH-12-A-2										
RES RX	Rotor	1X	10 / 3200	6'	1.0	8	20	32	250 + j850	330 + j1000
Multi-Speed - Part Number SSJH-15-A-2										
RES RX	Rotor	1X, 16X	5 / 6000	15', 60"	0.2, 0.2	5, 28	20, 2	250	139 + j236	69 + j45, 71 +j114

Products are subject to U.S. Government export license requirements.

Specifications and information are subject to change without prior notice.

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Americas

Moog Components Group
 1213 North Main Street
 Blacksburg, VA 24060
 United States

Tel: +1 540-552-3011
 Fax: +1 540-557-6400

Asia-Pacific

Moog Components Group
 Yokohama Nishiguchi KN Bldg. 10F
 2-8-4 Kitasaiwai, Nishi-ku
 Yokohama, Kanagawa 220-0004
 Japan

Tel: +81 45-328-1803
 Fax: +81 45-328-1801

Europe

Moog Components Group
 30 Suttons Business Park
 Reading, Berkshire RG6 1AW
 United Kingdom

Tel: +44 (0) 118-966-6044
 Fax: +44 (0) 118-966-6524

MOOG
 COMPONENTS GROUP

www.moog.com/components

Email: mcg@moog.com