

DC CUBE TORQUE MOTORS 21, 22, 23 AND SERIES



Moog's family of miniature permanent magnet DC cube torque motors is available in .075 and 1 inch frame sizes. These are rapid response motors at all operating speeds because of their high torque-to-inertia ratio and low self-inductance. Torque increases directly with input current for high linearity.

Cube motors are often used in applications where high torque is required, but the available space is limited. Cube motors lend themselves to easier mounting than cylindrical motors in many applications and are easier to lock into an envelope.

Moog offers a choice of Alnico or Samarium Cobalt magnet materials to satisfy most any requirement. These rare earth magnets produce a higher magnetic energy per unit volume than most commercially available permanent magnets. Alnico magnets provide enhanced temperature stability while Samarium Cobalt magnets offer high energy with good, stable performance.

We are tooled for hundreds of designs with different windings, end caps and other options including gearheads, brakes, resolvers, encoders and potentiometers. Most designs can easily be adapted to meet different requirements. We can also provide custom engineering services.

FEATURES

- 4 pole 13 bar motors 2 brushes standard and 4 brushes available
- Stainless steel shafts for durable, rugged wear
- Meets MIL-SPEC 810
- Standard nickel plated housing resists corrosion in harsh environments
- Peak torques from 1.0 to 20 oz-in
- Optional gearheads, brakes, resolvers, encoders and potentiometers available
- Available in 0.75 and $1 \mbox{ inch frame sizes}$
- Silver alloy brushes
- Speeds up to (7500) rpm
- Variety of windings available
- Gold plated terminals
- Gold alloy commutator
- Shaft can be modified with front and rear extensions, integrated gear or a pinio

BENEFITS

- High torque-to-inertia ratio in a small package
- Rapid response at all speeds
- Cartridge brush is easily field-replaceable
- Skewed rotors provide minimum cogging torque
- Gold-clad commutator for long life
- Rare earth magnets provide higher performance than standard permanent magnets
- Cubical shape provides weight and space savings and easy mounting
- Torque increases directly with input current for high linearity as a direct servo drive
- Low self inductance

CUBE MOTOR PARAMETERS

PART NUMBERING SYSTEM GUIDE

-AA - NN / ANNN[]NNN A NN HOUSING TYPE HOUSING CODE (3 Numbers) MODIFICATION NUMBER (Either Location) Sequentially DESIGN SÉRIES SHAFT P = Paladin black "D" + 3 Numbers assigned (2 Numbers) (2 Letters) S = Samarium Cobalt magnets ELECTRICAL OPTIONS Each modification number (slash by factory C = Connector (2 Numbers) number) has a separate outline FRAME SIZE Unique to design series modification sheet 21 1 inch square cube motor 22 1 inch square short version of series 21 23 1 inch square long version of series 21 **EXAMPLES OF TYPICAL CUBE MOTORS** 24 .75 inch square cube motor TERMINATIONS TYPE 1.21 Cube Series (1 Letter) • 1.02 in x 1.02 in x 1.069 in max 1.355 in x 1.355 in x 1.02 in max - cartridge screw type A Solder eyelet terminals (pin type terminals, 2 leaf springs) Peak Torques: 7.6 oz-in Alnico magnet B Lead out the rear 15.0 oz-in Samarium Cobalt magnet С (Not used) D Cover can and unshielded leads (radial exit) E (Not used) 2.22 Cube Series (Not used) 1.02 in x 1.02 in x 0.812 in max G (Not used) • Peak Torques: 3.6 oz-in Alnico magnet H (Not used) 7.0 oz-in Samarium Cobalt magnet (Not used) Leads out the side 1 K Turret type terminals 3.23 Cube Series Screw terminals #4-40, side exit with cartridge brushes (4) • 1.02 in x 1.02 in x 1.343 in max M Screw terminals #4-40, side exit with cartridge brushes (2) 1.355 in x 1.355 in x 1.500 in max - cartridge screw type N Pin type terminals with flush cartridge brushes (2) • Peak Torques: 12.0 oz-in Alnico magnet O (Not used) P (Not used) 20.0 oz-in Samarium Cobalt magnet Q Turret type terminals with flush (snap in) cartridge brushes (2) R Leads out the side with flush (snap in) cartridge brushes (2) 4.24 Cube Series S (Not used) • 0.750 in x 0.750 in x 0.750 in max Т (Not used) • Peak Torques: 2.7 oz-in Alnico magnet U 4 leaf springs, 2 pin terminals, 2 leads (2.7) oz-in Samarium Cobalt magnet V Pin type terminals with flush (snap in) cartridge brushes (4) W Leads out the side with flush (snap in) cartridge brushes (4) X 4 cartridge brushes, 2 pin terminals, 2 leads #2-64 screw terminals, 180° apart Z 4 leaf springs, 4 pin terminals TYPICAL APPLICATIONS • Avionics - cockpit instrumentation (altitude, latitude) and displays (indicators and instruments) • Robotic control systems Military targeting / fire control systems • Sighting systems feedback often within arc seconds of accuracy. Missiles Military actuators • Direct drive servo systems Medical equipment Integrated Motion Technology

In many gimballed systems for the military, aerospace and industrial market segments, rotary electromechanical components such as motors, resolvers and slip ring assemblies often find themselves sharing common envelopes and structures. For this reason, Moog has a unique niche in the marketplace by providing and integrating these traditional components into one assembly so the individual components have been optimized to work together.

Today, Moog is in the unique position to provide engineering and manufacturing expertise for all rotary components that share the gimbal's structure. Moog's fractional horsepower DC motors provide the torque for continuous rotation for scanning applications such as radar, missiles, seekers, aerial targets and target acquisition systems while the slip ring assemblies pass the power and data across the rotating interface. Our resolvers provide the positional

These components can, of course, be provided separately or be integrated. Integrated products typically share a common structure and bearing which reduces piece part count and system weight. Integration and test is performed at the factory providing a "plug and play" subsystem. Moog also provides complete actuator systems with control electronics. This integrated concept reduces the number of items that would otherwise have to be procured and stocked by the OEM.

System enhancements and upgrades occur naturally when dealing with one company that has the engineering and manufacturing expertise for rotary component needs.

SPECIFICATIONS ON TYPICAL CUBE MOTORS

The following tables presents a cross-section of Moog cube motor designs. Tooling charges may apply to new designs.

Part Number	Length	Peak Torque	Volts at Peak	Current at	Torque	Back EMF (V/rad/sec)	DC Resistance	Inductance	Inertia (oz-in-sec2)	No Load	No Load	Starling	Weight
	(metric)	(Nm)	(Volts)	(amps)	(oz-in/amp)	(Nm/amp)	(Ohms)	(mH)	(KgCm2 x10E-4)	(RPM)	(Ma)	(Volts)	(gm)
21105N-□□-03	1.06	7.5	26.0	1.7	5.3	3.74	15.0	6.0	1.3	6500	85	1.0	2.93
	26.9	.053	26.0	1.7	.037	3.74	15.0	6.0	.018	6500	85	1.0	83.06
21105A-□□-04	1.06	7.5	41.7	0.975	7.55	5.3	44.0	16.0	1.3	6500	60	0.75	2.93
	26.9	.053	41.7	0.975	.053	5.3	44.0	16.0	.018	6500	60	0.75	83.06
21105N-□□-08	1.06	8.6	13.0	3.3	2.6	1.8	3.9	1.3	1.3	6500	150	1.0	2.93
	26.9	.061	13.0	3.3	.018	1.8	3.9	1.3	.018	6500	150	1.0	83.06
21105N-□□-10	1.06	6.0	8.0	5.0	1.2	0.85	1.6	0.4	1.3	6500	225	1.0	2.93
	26.9	.042	8.0	5.0	.009	0.85	1.6	0.4	.018	6500	225	1.0	83.06
21105N-□□-12	1.06	6.5	26.0	1.7	4.6	3.25	15.0	6.0	1.3	7000	85	1.0	2.93
	26.9	.046	26.0	1.7	.033	3.25	15.0	6.0	.018	7000	85	1.0	83.06
21105N-□□-13	1.06	6.5	41.7	0.975	6.7	4.8	44.0	16.0	1.3	7000	60	1.0	2.93
	26.9	.046	41.7	0.975	.048	4.8	44.0	16.0	.018	7000	60	1.0	83.06
21605A-□□-14S	1.06	11.0 min.	20.5	2.95	3.8	2.68	7	3.3	1.3	7000	217	1.0	2.93
	26.9	.078	20.5	2.95	.027	2.68	7	3.3	.018	7000	217	1.0	83.06
21607A-□□-15S	1.06	12.0 min.	24	3.5	4.75	3.35	7.5	3.5	1.3	6500	90	0.75	2.93
	26.9	.85	24	3.5	.034	3.35	7.5	3.5	.018	6500	90	0.75	83.06
21607J-□□-16S	1.06	8.5	20	1.5	5.5	3.9	13	5	1.3	4600	100	1.5	2.93
	26.9	.060	20	1.5	.039	3.9	13	5	.018	4600	100	1.5	83.06
21607J-□□-19S	1.06	12.0	25.9	2.9	5.0	3.5	9	4	1.3	6800	60	1.0	2.93
	26.9	.085	25.9	2.9	.035	3.5	9	4	.018	6800	60	1.0	83.06
21605A-□□-20S	1.06	12.0	28	3.2	5.4	3.8	10.5	5	1.3	6700	60	0.75	2.93
	26.9	.085	28	3.2	.038	3.8	10.5	5	.018	6700	60	0.75	83.06
21105K-□□-22S	1.06	7.2	12	2.1	4.5	3.2	7	3.3	1.3	3400	60	1.0	2.93
	26.9	.051	12	2.1	.032	3.2	7	3.3	.018	3400	60	1.0	83.06
22613J-□□-01	0.812	3.6	26.0	0.6	6.0	4.2	43.0	12.0	0.65	5000	45	1.0	2.0
	20.6	.025	26.0	0.6	.042	4.2	43.0	12.0	.009	5000	45	1.0	56.70
22613M-□□-01	0.812	3.6	26.0	0.6	6.0	4.2	43.0	12.0	0.65	5000	45	1.5	2.0
	20.6	.025	26.0	0.6	.042	4.2	43.0	12.0	.009	5000	45	1.5	56.70
23101L-□□-01	1.50	10.0	26.0	2.1	4.8	3.4	12.0	5.0	2.2	5800	125	1.0	4.3
	38.1	.071	26.0	2.1	.034	3.4	12.0	5.0	.031	5800	125	1.0	121.9
23101L-□□-02	1.50	12.0	18.0	3.27	3.7	2.6	5.5	2.2	2.2	5500	175	1.0	4.3
	38.1	.085	18.0	3.27	.026	2.6	5.5	2.2	.031	5500	175	1.0	121.9
24618R-□□-04	0.75	1.7	15.0	0.58	3.7	2.6	26.0	8.5	0.35	5000	50	1.5	1.25
	19.1	.012	15.0	0.58	.026	2.6	26.0	8.5	.005	5000	50	1.5	35.44
24618N-□□-05	0.75	2.7	12.0	1.0	2.7	1.9	12		0.35	5725	50	1.0	1.25
	19.1	.019	12.0	1.0	.019	1.9	12		.005	5725	50	1.0	35.44
24618R-□□-09	0.75	1.0	6	0.75	1.35	0.95	8	1.4	0.35	6000	125	1.0	1.25
	19.1	.007	6	0.75	.010	0.95	8	1.4	.005	6000	125	1.0	35.44
24618V-□□-10	0.75	2.5	26	0.425	5.75	4.1	61		0.35	5500	30	1.0	1.25
	19.1	.018	26	0.425	.041	4.1	61		.005	5500	30	1.0	35.44
24618V-□□-11	0.75	1.5	15.0	0.555	2.7	1.9	22.5		0.35	6600	75	1.25	1.25
	19.1	.011	15.0	0.555	.019	1.9	22.5		.005	6600	75	1.25	35.44
24618V-□□-15	0.75	1.0	7.5	0.575	1.8	1.3	13	1.4	0.35	5000	70	0.75	1.25
	19.1	.007	7.5	0.575	.013	1.3	13	1.4	.005	5000	70	0.75	35.44

Part Number	Length	Peak Torque	Volts at Peak ^{Torque}	Current at Peak Torque	Torque Constant	Back EMF	Term. Res.	Term. Ind.	Rotor Inertia	Frictional Torque	Motor Constant	Weight		Pot. End-End Travel	Pot. Linearity
	(inches)	(ozin.)	(Volts)	(amp)	(oz.in./amp)	(V/Rad./s)	(Ohms)	(mH)	(oz.in.s ²)	(oz.in.)	(oz.in./sq.rt.watts)	(oz.)	(Commutation)		
DC MT/POT															
AS-889-003	1.500	12.0	21.6	2.40	5.00	0.035	9.00	4.50	1.6E-04	0.30	1.67	4.0	Potentiometer	250°	Absolute +/50%
MT/RESOLVER															Transformation
AS-891-002	2.000	1.3	13.3	0.42	3.50	0.025	32.00	6.00	7.8E-06	0.20	0.62	3.2	Resolver	Accuracy < 6'	Ratio 0.454 +/- 5%
MT/POT/GHD														Gear Ratio	
AS-915-001	3.375	66.5	26.1	2.90	5.50	0.039	9.00	4.50	3.0E-04	3.50	1.83	6.0	None	4.84:1	Back Lash < 0.5°

CUBE MOTOR TYPICAL OUTLINES

MECHANICAL DIMENSIONS IN INCHES (MILLIMETERS)



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CUBE MOTOR OUTLINES

