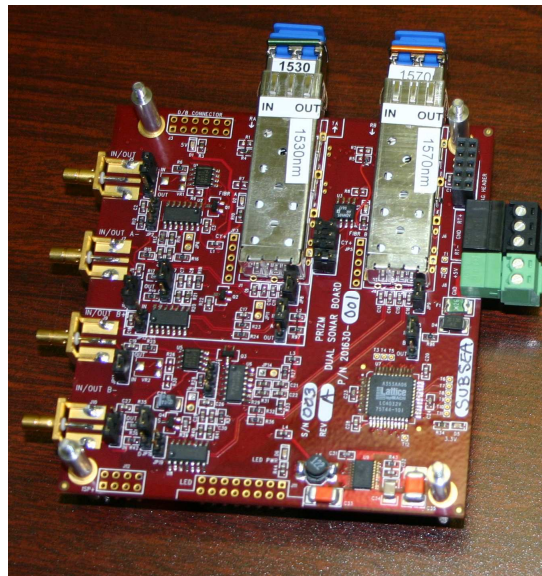




## Mini4 Dual Sonar Interface Board (P/N 201630-xxx)

### User's Manual And Troubleshooting Guide



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MANUAL REVISION HISTORY

REVISION NUMBER	DATE	BY	REASON FOR REVISION
Preliminary	10/26/06	GSG	ORIGINAL
A	4/19/09	GSG	UPDATED
B	2/23/09	IB	Updated contact information to reflect Moog Components Group

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## **1 Mini4 Dual Sonar Board, P/N: 201630-xxx**

The Prizm Mini4 Dual Sonar Board provides two independent fiber optic links to remote the Reson 8xxx and Simrad EM3002 single/dual beam sonars. The Dual Sonar Board can be jumper selected to support both single-ended (single coax) Reson sonars and differential (dual coax) Simrad sonars. This board only provides for the sonar's uplink (subsea to surface) data link, the downlink (surface to subsea) control link must be handled through another separate multiplexer. The control link for the Reson and Simrad sonars may require specific electrical protocols (i.e. RS-232, RS-485, RS-422 or other) and the sonar manufacturer's interface manual should be consulted.

The Dual Sonar Board can be jumper configured to operate as either a subsea or surface interface board, so can be used as spare for either location. The optical modules used on the board (pluggable small-form-factor (SFP)) are inherently bi-directional and care must be taken to ensure the correct optical port (either TX or RX) is connected, depending on the board configuration and system location. While the optical module's receiver will operate on all of the 16 CWDM wavelengths (1270 to 1610nm), the module's transmitter only emits at a single wavelength so care must be taken to ensure the correct wavelength is used.

The Dual Sonar Board supports PMON II diagnostics through the RS-485 diagnostics cable. Diagnostics will display the optical parameters from both of the SFP modules and will also show the sonar activity (both into and out of the board) on PMON II. Note: to acquire diagnostics from the remote Dual Sonar Board, the board must be either stacked on top of a Mini4 Video Input or Output board or have its 3-pin Phoenix diagnostics cable connected to a Mini4 Video Input or Output board.

### **1.1 Mini4 Dual Sonar Board Revision History:**

The Mini4 Dual Sonar Board has gone through the following printed circuit board (PCB) and Assembly revisions:

PCB Revision A/Assembly Revision A Original design..

### **1.2 Mini4 Dual Sonar Board Dash (-) Number Definitions**

The Mini4 Dual Sonar Board has a Dash Number appended to the part number. This Dash Number identifies the specific board configurations:

-001 original configuration.

### **1.3 Mini4 Dual Sonar Board Operation:**

Each independent sonar link has two 50-ohm SMB coaxial connectors. These connectors will be active as inputs or outputs depending on the jumper settings. For single-ended (single coax) sonars, only the top SMB connector will be active (labeled IN/OUT A+ or IN/OUT B+). For differential (dual coax) sonars, both of the connectors will be used.

The sonar fiber links are identified as link "A" or "B".

There is single green 2-pin Phoenix connector on the on the right side of the board for supplying the board with +5VDC. Pin 1 is the +5VDC input and pin 2 is the ground.

There is single black 3-pin Phoenix connector on the on the right side of the board for RS-485 diagnostics. Pin 1 is the RT+ signal, pin 2 is the ground/shield and pin 3 is the RT- signal. A Prizm Diagnostics cable can be connected directly to this 3-pin connector or through a stacked Mini4 Video Input or Output board.

NOTE: To complete the RS-485 diagnostics link from the surface to the subsea boards, the Dual Sonar Board must be stacked onto a Mini4 Video Input or Output board to complete the link over the multiplexer's fiber.

### 1.3.1 Dual Sonar Board Indicators and Controls:

#### LEDS:

There are 4 surface mount vertical LED indicators on the top of the board and 4 surface mount right-angle LED indicators on the bottom of the board.

#### Top of Board

LED	Indication
D1 (Green)	Located at the top left of the board serves as an indicator that +5V DC is available to the board. Supply voltage 5V to the board is selected via the placement of fuse F1 (or F2 or F3).
D2 (Green)	Located on the top center of the board, labeled 'FIBR A', provides an indication that the transceiver module has detected the presence of an input signal on the fiber link. When 'ON' indicates that this board has a good level of received optical power from the remote unit A.  NOTE: IF BOARD IS CONFIGURED AS AN INPUT, THEN THIS LED WILL BE OFF.
D3(Green)	Located on the top center of the board, labeled 'FIBR B', provides an indication that the transceiver module has detected the presence of an input signal on the fiber link. When 'ON' indicates that this board has a good level of received optical power from the remote unit B.  NOTE: IF BOARD IS CONFIGURED AS AN INPUT, THEN THIS LED WILL BE OFF.
D5(Green)	Located at the bottom right of the board serves as an indicator that +3.3V DC is operational on the board. 3.3V is generated by the on-board DC-DC converter at U9.

#### Bottom of Board

LED	Indication
D10 (Green)	'ON' when sonar data is being sent out of the board on link A
D15 (Green)	'ON' when sonar data is being received into the board on link A
D16 (Green)	'ON' when sonar data is being sent out of the board on link B
D19 (Green)	'ON' when sonar data is being received into the board on link B

**FUSES:**

There are four fuses for this board, all fuses are the self-resetting PTC type and will not require replacement by the user.

**F1:** 2.6 Amp PTC, +5VDC input fuse at J8

**F2:** 2.6 Amp PTC, +5VDC input fuse for Diag header at J4 – NOT PLACED

**F3:** 2.6 Amp PTC, +5VDC input fuse for Daughterboard header at J3  
– NOT PLACED

**F4:** 0.5 Amp PTC, +5VDC output fuse for LED header – NOT PLACED

**SWITCHES:**

There are no switches on this board.

**CONNECTORS:**

The fiber optic modules are identified as connectors,

**J1:** Optics module “A”

**J2:** Optics module “B”

There are four SMB coaxial connectors on the left side of the board for connecting the sonar coaxial cables.

**J5:** “IN/OUT A+”, single-ended input/output or differential positive input/output

**J7:** “IN/OUT A-”, not used if single-ended or differential negative input/output

**J9:** “IN/OUT B+”, single-ended input/output or differential positive input/output

**J10:** “IN/OUT B-”, not used if single-ended or differential negative input/output

There are two daughterboard stacking connectors.

<b>J3</b>	Daughterboard Header			
VDC Supply	1	o o	2	VDC Supply
RXD_DB	3	o o	4	TXD_DB
GND	5	o o	6	GND
RXC_DB	7	o o	8	TXC_DB
RCV LINK	9	o o	10	Future
RXD_DB2	11	o o	12	TXD_DB2

<b>J4</b>		Diagnostics Header			
	RT+	1	o o	2	RT-
	GND	3	o o	4	GND
	GND	5	o o	6	GND
	+5V	7	o o	8	+5V
	+5V	9	o o	10	+5V

There are two Phoenix pluggable connectors

**J6:** 3-pin Phoenix, RS-485 Diagnostics

<b>J6</b>		Diagnostics Connector	
o	1	RT+	
o	2	GND	
o	3	RT-	

**J8:** 2-pin Phoenix, +5VDC power entry

<b>J8</b>		+5VDC Power Connector	
o	1	+5V	
o	2	GND	

There is one 16-pin ribbon header for remote LED diagnostics display

**J11:** 16-pin ribbon, LED diagnostics

<b>J11</b>		Led Status Connector			
	GND	1	o o	2	PTC FUSE with +5VDC
	FIBER A LED	3	o o	4	FIBER B LED
	* IN ACT A LED	5	o o	6	IN ACT B LED *
	* OUT ACT A LED	7	o o	8	OUT ACT B LED *
	No connect	9	o o	10	No connect
	No connect	11	o o	12	No connect
	No connect	13	o o	14	No connect
	No connect	15	o o	16	No connect

**NOTE 1:** J11 header is located at the bottom center side of the board.

Pin 1 is the upper right pin – as identified by a square pad.

**NOTE 2:** Signals are active low.

**NOTE \*:** These signals not available on PCB Rev A boards.

There is one header for programming the Lattice programmable device

**J12:** ISP programming header, do not use

J12	ISP Header				
	+3.3V	1	o o	2	TMS
	TCK	3	o o	4	TDI
	N/C	5	o o	6	TDO
	GND	7	o o	8	

**NOTE:** J12 to be used only by PRIZM.

### JUMPER POSTS:

The board contains jumper posts to allow the user to configure each link for input or output and for single-ended or differential signals. Other jumpers are used for factory programming or testing and should not be move or changed.

**For link “A”**, jumper posts JP1, 2, 7, 8, 10, 12, 21 are selectable.  
(PIN 1 DENOTED BY SQUARE PCB PAD)

**JP1:** Input/Output select for IN/OUT A+ connector (J5)

1 o IN	1 o IN
2 o for INPUT	2 o for OUTPUT
3 o OUT	3 o OUT

**JP2:** Output A CD/Mute Selection

3 o	3 o	3 o
2 o Disable Mute	2 o for CD Mute	2 o for LSI Mute
1 o	1 o	1 o

**JP7:** Single-ended/Differential select for link A

3 o S	3 o S
2 o for Single-ended	2 o
1 o D	1 o D

**JP8:** Laser enable/disable select for link A

2 o		2 o
	to enable laser	to disable laser
1 o		1 o

**JP10:** Input/Output select for IN/OUT A- connector (J7)

3 o OUT		3 o OUT
2 o for INPUT		2 o for OUTPUT
1 o IN		1 o IN

**JP12:** Input A CD/Mute Selection

1 o		1 o
	Disable Mute	for CD Mute
2 o		2 o

**JP21:** Input/Output select for link A

1 o IN		1 o IN
2 o for INPUT		2 o for OUTPUT
3 o OUT		3 o OUT

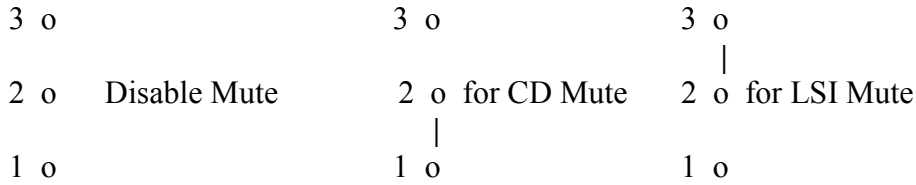
**For link "B"**, jumper posts JP9, 13, 15, 17, 18, 19, 20 are selectable.  
(PIN 1 DENOTED BY SQUARE PCB PAD)

**JP13:** Input/Output select for IN/OUT B+ connector (J9)

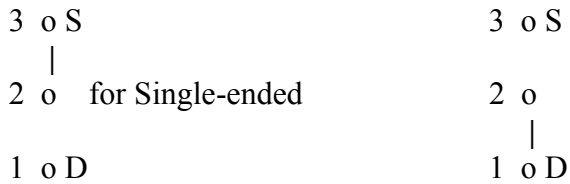
1 o IN		1 o IN
2 o for INPUT		2 o for OUTPUT
3 o OUT		3 o OUT



**JP15:** Output B CD/Mute Selection



**JP18:** Single-ended/Differential select for link B



**JP9:** Laser enable/disable select for link B



**JP17:** Input/Output select for IN/OUT B- connector (J10)



**JP19:** Input B CD/Mute Selection



**JP20:** Input/Output select for link B

1 o IN  
 |  
 2 o for INPUT  
 3 o OUT

1 o IN  
 2 o for OUTPUT  
 |  
 3 o OUT

**For factory configuration**, jumper posts JP3-6, 11, 14, 16 are selectable.  
 (PIN 1 DENOTED BY SQUARE PCB PAD)

**JP3:** Cypress “A” microprocessor programming header – do not use

**JP4:** RS-485 Diagnostics enabling header

1 o==o 2	1 o o 2
3 o o 4 To enable “A” Only	3 o== o 4 To enable “B” Only
5 o==o 6	5 o o 6
7 o o 8	7 o== o 8

1 o==o 2  
 3 o==o 4 To enable both “A” and “B”  
 5 o==o 6  
 7 o==o 8

**JP5:** Cypress “B” microprocessor programming header – do not use

**JP6:** Eye monitor, “A” Output

1 o test point  
 2 o GND

**JP11:** Eye monitor, “A” Input

1 o test point  
 2 o GND

**JP14:** Eye monitor, “B” Output

- 1 o test point
- 2 o GND

**JP16:** Eye monitor, “B” Input

- 1 o test point
- 2 o GND

**1.3.2 Mini4 Dual Sonar Board Specifications:**

Number of Sonar links:	2 per board
Sonar type supported:	Reson 8xxx or Simrad EM3002
Data rates supported:	Depends on sonar
Maximum Sonar data rate:	600Mbps

**1.3.3 Mini4 Dual Sonar Board Dimensions:**

Printed circuit board (PCB): 3.55 in x 3.775 in x 0.60 in board-to-board  
(90.1mm x 95.88 mm x 15.24 mm)

**1.3.4 Dual Sonar Board Power Requirements:**

The Dual Sonar Board utilizes approximately 650mA @ 5VDC.

**1.3.5 Power Section Testing**

***NOTE: The connectors on the bottom of the Dual Sonar Board have pins that are connected to +5VDC and ground. If these pins are inadvertently shorted together or to a common chassis ground, the board fuse (F1) will trip/reset.***

If both the +5V Power LED +3.3V Power LED are out:

- Check for continuity of PTC fuse F1 with an ohmmeter.
- Replace PTC fuse if open.

If only the +5V Power LED is out:

- Verify +5V DC is present at the source
  - At J8 if powered off of external power
  - At J3 or J4 if powered off of the stacking connectors.
- If +5V is not available replace the board with a spare.
- If +5V is available check the display LED (D1).

If only the +3.3V Power LED is out:

- Verify +5VDC at F1 or J8 (replace board if +5VDC is not available)
- Verify +3.3VDC across C33 on top of board
  - If +3.3V is not available replace the board with a spare.
  - If +3.3V is available check the display LED (D5).

### 1.3.6 Optical Section Testing

For surface boards, if the “FIBR A” or “FIBR B” LED is off or flickering, one or more of the following conditions is likely:

- The fiber is broken or damaged.
- The optical transceiver module is defective at either the surface or subsea board.
- Excessive light loss (low received optical power) is being experienced.
- The Mini4 board (not the optical transceiver module) is malfunctioning.
- There is not enough attenuation in the optical link and the receiver is saturating.

If excessive optical loss is being experienced, the following conditions may be present:

- May have sonar data errors.
- Check the optical level with an optical power meter and inspect all fiber optic connections including CWDMs and slip rings.

To determine if the fiber is broken, a laser module is out, or the board is malfunctioning, first:

- Verify that the optical transceiver is tight in its socket.
- Verify that shunts (jumpers) are placed per system jumper configuration.
- Check all fiber optic connections including CWDMs and slip rings to make sure that they are not causing the problem.
- Check that the optical fiber cable is straight at connectors on board for minimum optic loss.

### 1.3.7 Sonar Testing

If one or both sonar data channels (links) are out or has errors:

- Using a signal generator set for about 5MHz squarewave with a amplitude of about 1Vp-p, insert this signal into appropriate connector (J5 or J9) of the channel being tested. The test signal should be input into subsea (vehicle) Dual Sonar board.
- On the other end of the link, connect an oscilloscope to the corresponding connector (J5 or J9). Verify that there is a 5MHz squarewave being output from the surface Dual Sonar board and that the signal is not distorted or has glitches (noise) in the signal.
- If the channel is not operating correctly, first check the field wiring. If the wiring appears correct, then first replace the subsea Dual Sonar board with a spare and check the sonar link again. If the problem is still there, replace the surface Dual Sonar board, with a spare and check the link again.

- If any of the LEDs are not operating correctly check one of the other channels. If the LEDs operate on that channel, replace the Mini4 board with a spare board or use the working channels only.

## 1.4 Stack Mini4 System Installation Checkout Procedure

NOTE: The Dual Sonar Board will work in a stand-alone configuration without stacking the boards above a Mini4 Video Input or Output board. Without a Mini4 Video board, the subsea diagnostics will not work but the board will still carry a sonar signal.

For this PC/104 stack Mini4 System installation checkout procedure, it is assumed that the Mini4 System is composed of a Video Input board mounted in the vehicle and a Video Output board on the surface. +5VDC power for the Mini4 boards is supplied by the user's DC power supply powering the PC/104 stack and should be verified to be between +4.75VDC and +5.25VDC at the 2-pin Phoenix power connector.

### 1.4.1 Diagnostics Overview

The Dual Sonar Board has been designed to include hardware and firmware for monitoring various parameters of interest. This capability is accessed via a 3-pin Phoenix connector on the board that carries bi-directional RS-485 telemetry. The diagnostics will typically be used in conjunction with a user-supplied PC on the surface, which has been loaded with PRIZM Modem Monitoring S/W (PMON II).

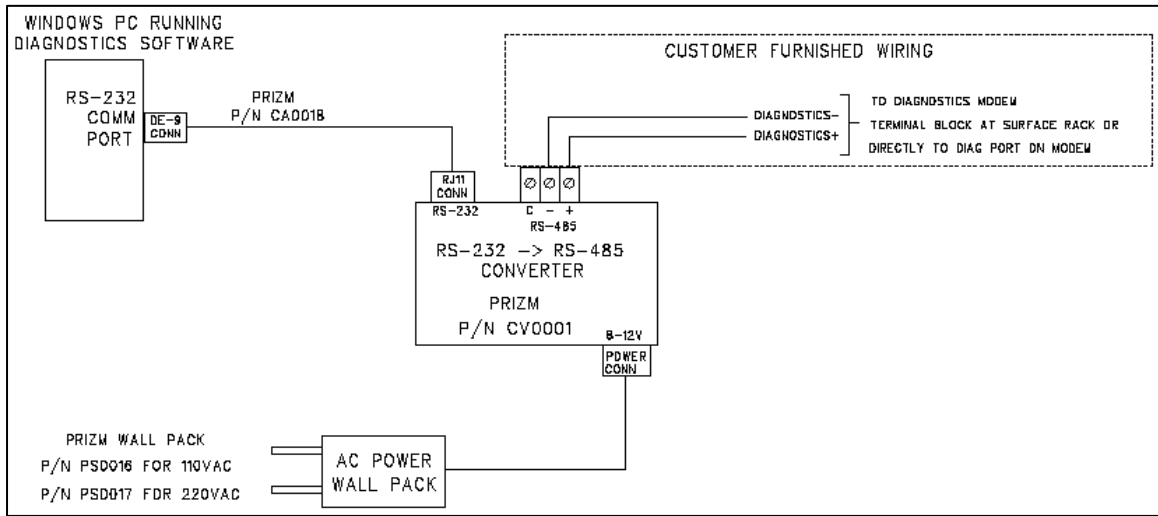
For the Dual Sonar board, the Diagnostics feature requires that there be a functioning multiplexer system for connectivity between the topside Diagnostic PC and the remote multiplexer. The Mini4 Video Input and Output board have a transparent link for carrying the Diagnostics across the fiber link and does not require a user's RS-485 channel. If the Dual Sonar board is stacked on a Mini4 Video Input or Output board diagnostics is automatically connected.

**NOTE: The diagnostics feature in no way interferes with normal operation of the modem – it is not necessary to be running the diagnostics software for any of the Mini4 boards to work.**

### 1.4.2 Required Communications Hardware for Diagnostics

The diagnostics capability is accessed via the 3-pin Phoenix connector on the Mini4 boards, which provides the RS-485 connectivity to the on-board processor for diagnostics communications. RS-485 was used because of its multi-drop capability, which in this case allows all the Mini4 boards to be communicated with via a single channel. In this configuration, no RS-485 multiplexer channel is needed.

The user is required to communicate with the Mini4 boards of the system via RS-485. A typical installation is shown in the following drawing. This details a diagnostic connection from a Windows PC running PMON II to a Mini4 board stack.



**Figure 1- Typical Cabling/Wiring for Back plane Diagnostics Telemetry**